



FICCI Conference, New Delhi

Technology Development - New Technologies

April 18./19.2016 | Andreas Grunicke thyssenkrupp Marine Systems – Operating Unit Submarines

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- 5. Hydrodynamics, propeller development
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- 7. UUV integration concepts
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thyssenkrupp – Organizational overview

thyssenkrupp Business Areas



Key indicators – fiscal year 2014/2015¹⁾

1) Continuing operations (after reclassification of Steel Americas) before consolidation. 2) Adjusted before consolidation, after definition changes



thyssenkrupp Marine Systems – Operating Units

Business Unit thyssenkrupp Marine Systems



Atlas Elektronik



Generic Tasks of Research and Development

Mid- and Long-Term Enhancement of Competitiveness

Technology Leadership

Cost Leadership

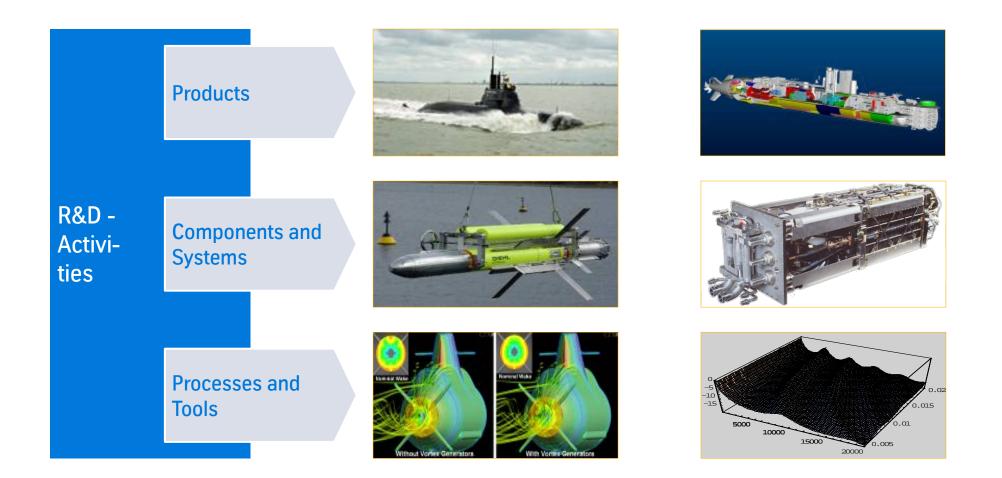
Enhancement of Customer Value

Cost Reduction

Risk Reduction

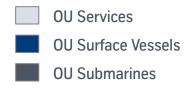


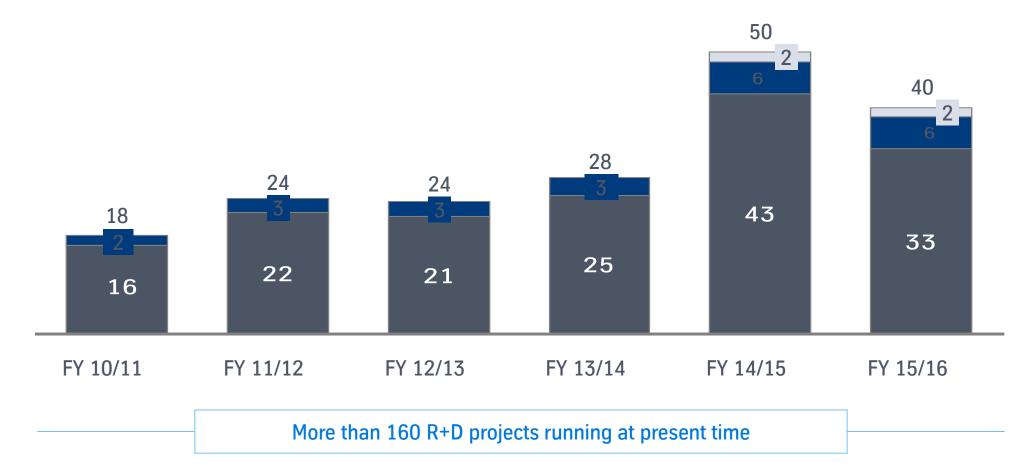
Scope of Research and Development Activities





Research& Development Expenditure Mio. EUR

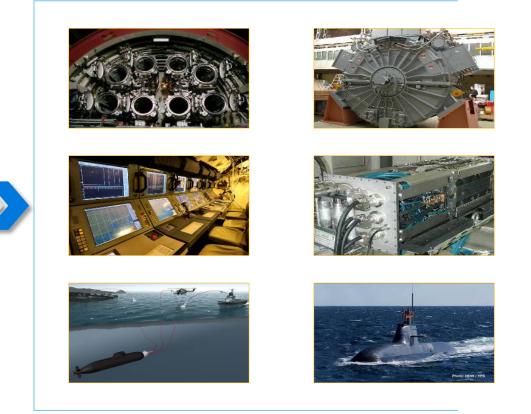






Long Lasting Developments¹

Weapon Section	<i>1988 - 1994</i>
Torpedo Counter Measures	<i>1999 - 2005</i>
ISUS 90 Family	1990 - 2005
PERMASYN® Motor	<i>1985 - 2005</i>
Fuel Cell System	<i>1980 - 2005</i>
IDAS	<i>1996 -</i>
Lithium Battery System	2003 -
Class 212	<i>1987 - 2005</i>
Class 214	<i>1996 - 2007</i>



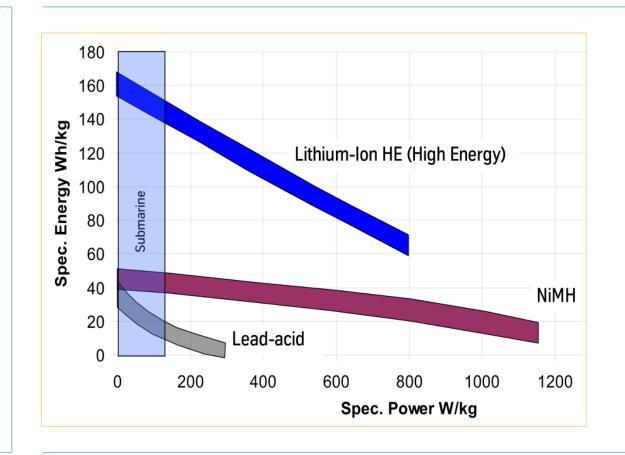
1 From start of development to delivery of first submarine with this technology



Lithium Ion Batteries - Introduction and Motivation

To Improve Operational Value of the Submarine

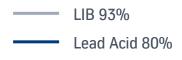
- Extend time submerged
- Increase speed spectrum while submerged
 - Complement to the AIP-System designed to fulfill low power requirements
- Decrease indiscretion rate
 - Improved charging and discharging characteristics
- Increase availability
 - Decrease maintenance requirements
- Decouple submarine performance from battery characteristics (as much as possible)
 - High speed independent from State of Charge (SoC)
- Extend life time.

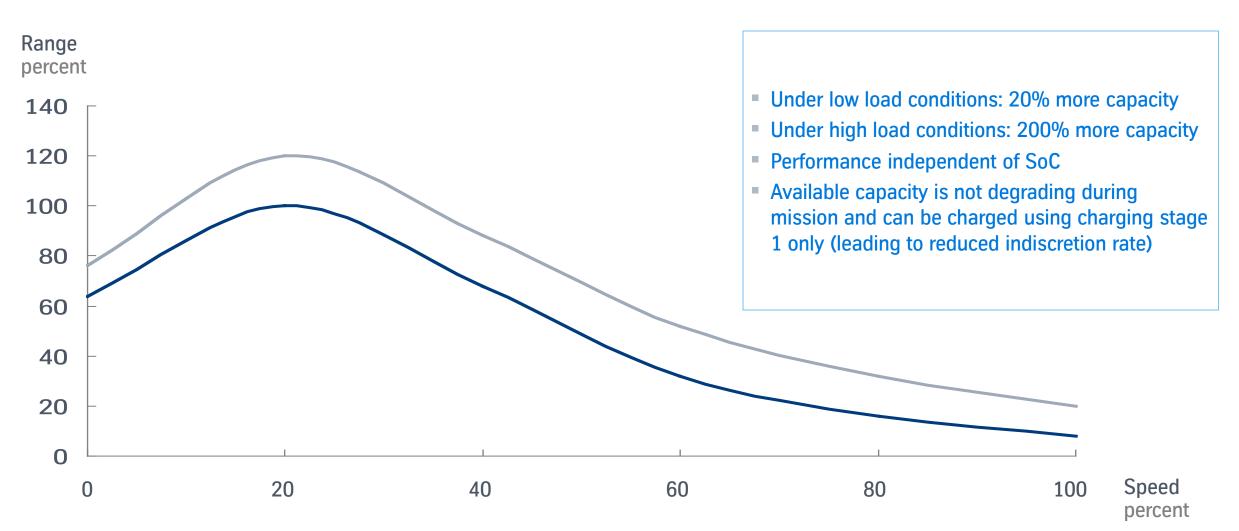




Technical Concept

How about Performance?

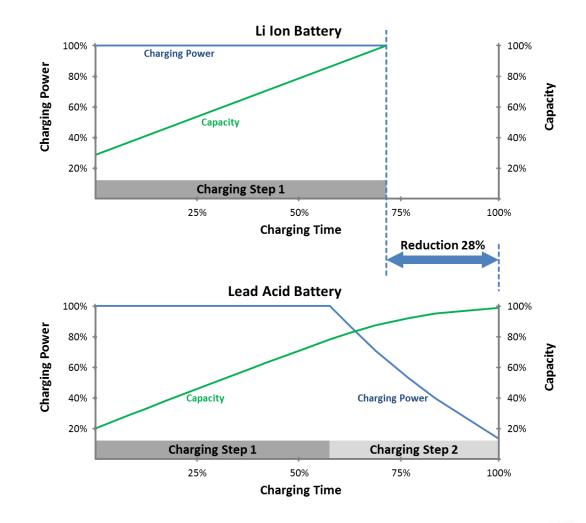






Comparison of Charging Times

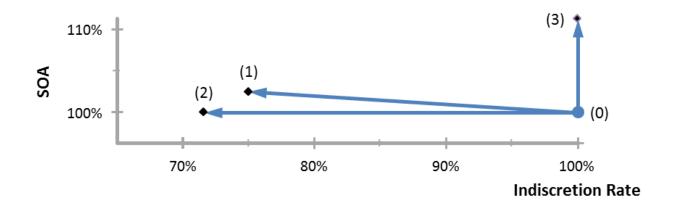
- Boundary Conditions
 - Both batteries are discharged with the same charging power
 - Both batteries are discharged the same time (same discharged energy)
 - Both batteries are charged with the same max. charging power
 - Lead Acid Battery: Charging Step 1 with max. power, charging step
 2 with max Voltage and reduced current (= reduced charging power)
 - Li Ion Battery: Only charged in charging step 1
 - The charging time of the Li Ion battery is approx. 28% less than the charging time of the lead acid battery. This means improved Indiscretion Rate

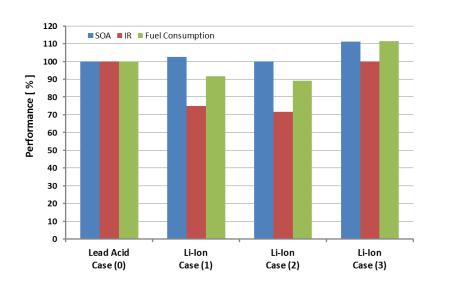


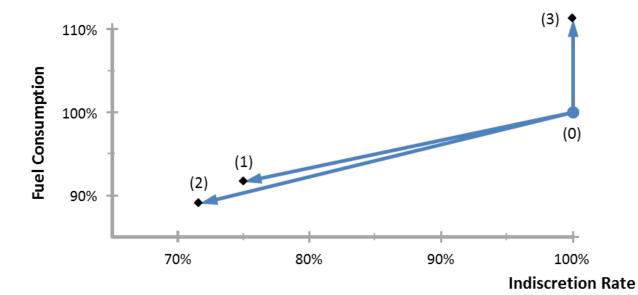


Optimization of Transit SOA

- Lead Acid Battery
 - Case (0): Optimized transit SOA for Indiscretion Rate
- Li-Ion Battery
 - Case (1): Same speed combination as in case (0)
 - Case (2): Same SOA as in case (0)
 - Case (3): Same IR as in case (0)







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Major Integration Aspects

System Safety is Critical!

Risk	 Thermal Runaway and the chain reaction within the battery compartment High Energy Chemistries bear the risk of open fire in the battery compartment NCA – Nickel-Cobalt-Aluminum NMC – Nickel-Manganese-Cobalt NCO – Nickel-Cobalt-Oxide 	
Trigger	OverchargeOverload	To be handled by control electronics
	OverheatMechanical Damage	To be handled by mechanical integration
	Internal Short	A manufacturer's quality assurance issue with a remaining risk

- There are intrinsically safe chemistries
 - LFP Lithium-Iron-Phosphate.

A damage and risk assessment lead to high safety integrity level (>= SIL4) requirement for the control electronics when NCA/NMC/NCO is used.



Battery Development at thyssenkrupp Marine Systems

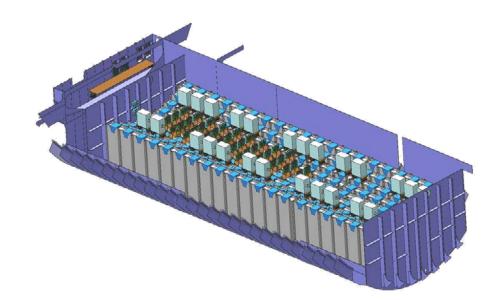
Decision

- Selection of well established cell manufacturer with system development competency
- Standard cell as core element
- Selection of LFP (blend) as the cell chemistry
- Focus on system integration as thyssenkrupp Marine Systems expertise.



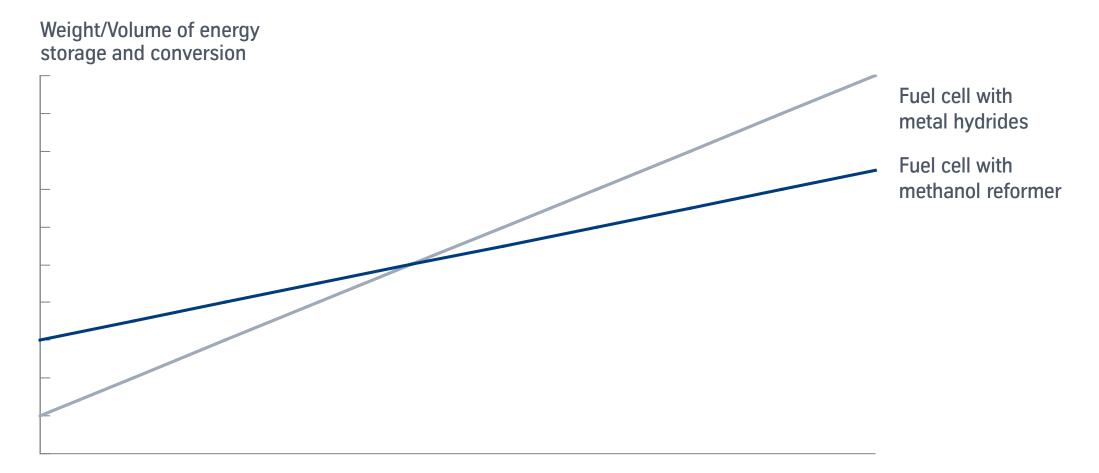
Lithium-Ion Battery Integration into the Submarine

	Cl. 214
Number of modules transversal	12
Number of modules longitudinal	2 x 16
Module voltage [V]	89 - 125
Energy per module [kWh]	38
Total number of modules	384
Number of modules per string	6
String voltage range [V]	535 - 752
Engine voltage range [V]	520 - 830
Number of strings	64
Total number of cells	101376
Energy [MWh]	14,5





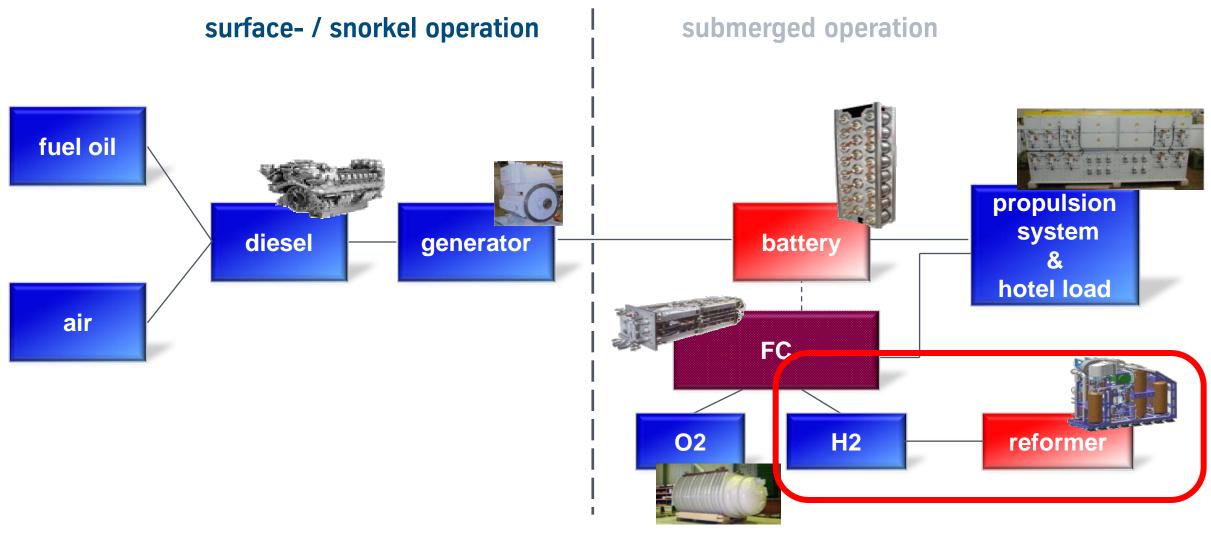
Methanol Reformer – Why start the Development



AIP energy to store



Power Supply



Source: Siemens, Gaia, MTU, Piller



Hydrogen Generation by Methanol Steam Reforming

- Simple alcohol CH₃OH
- Lowest reforming temperatures of 250° 300°C
- Cheap and easily available worldwide (like LOX)
- Methanol steam reforming is a proven technology in the process industry

$$CH_3OH + H_2O \Rightarrow 3H_2 + CO_2$$

Best choice for hydrogen generation on submarines

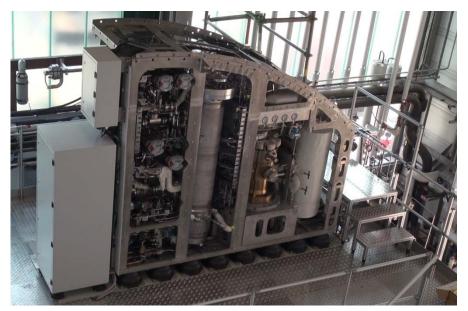


Fuel Cell Methanol Reformer System

The Fuel Cell Methanol Reformer System (FCMRS) combines the advantage of the existing, proven Fuel Cell System with the advantage to utilize a liquid fuel with high energy density. A first demonstrator has been operated since the year 2000

The reformer prototype system has been set into operation in the test field at thyssenkrupp Marine Systems premises in Kiel in summer 2015.

The system has already successfully produced ultra-pure hydrogen. Furthermore the Fuel Cell Modules have been operated on hydrogen produced by the reformer system.



Methanol Reformer



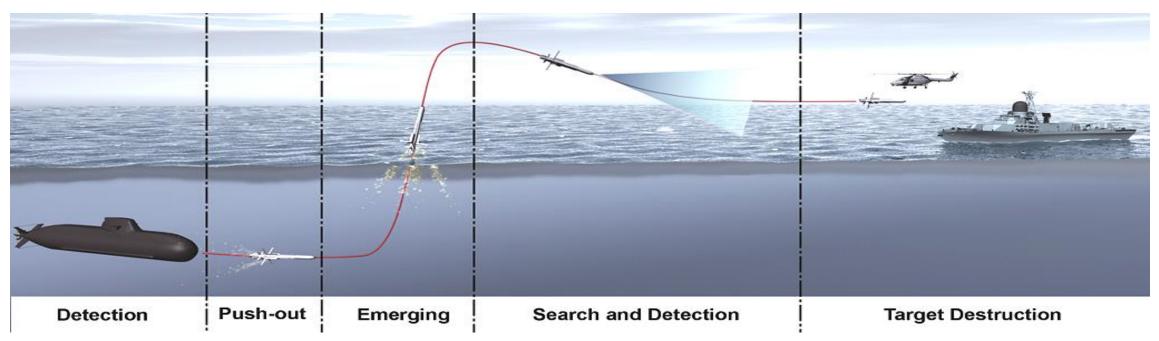
Fuel Cell Modules



IDAS at a Glance

- IDAS Changing the paradigms of anti submarine warfare!
 - Active self defence against airborne ASW for submerged submarines
 - High precision through Human in the Loop Concept
 - Coastal and small surface targets attack capability







Operational Concept

The IDAS Target Spectrum

Defensive Role













Weapon of choice for targets which are too fast or not accessible for a heavy weight torpedo, or for which a torpedo is over dimensioned



Technical Concept

• IDAS Submarine Integration

Very easy integration, handling with existing equipment for standard heavy weight torpedoes



Operator controlled during the whole mission





Technical Concept

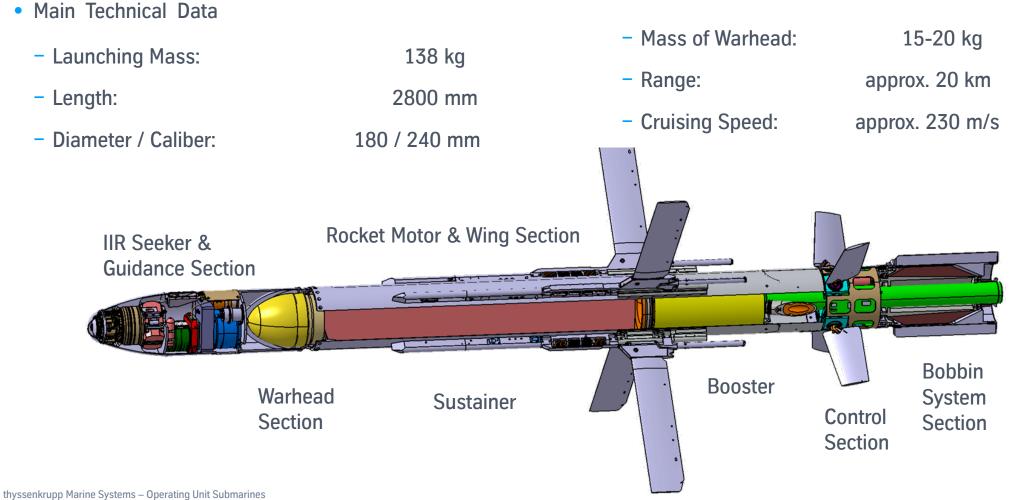
- IDAS Launching Container System
 - Four (4) missiles per launching container
 - All launching subsystems in container (autonomy)
 - Weight/ dimensions comparable to heavy weight torpedo, easy retrofit to all standard torpedo tubes







The IDAS Missile





Unmanned Underwater Vehicles on Submarine

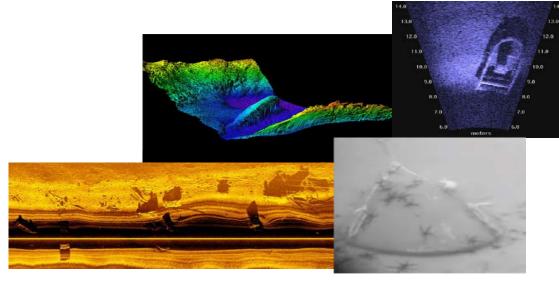
- What is the original purpose of unmanned underwater vehicles?
- Normally
 - AUVs bring sensors from the surface
 - down in the ocean
 - close to the targets
 - away from disturbing noise and vibrations
- Submarines
 - AUVs bring sensors from down into the ocean
 - away from the submarine
 - to areas of very shallow waters
 - to the surface
 - to areas with a high risk for <u>Manned Underwater Vehicles</u>.





Tasks of UUVs Deployed by Submarines

- Rapid environmental assessment (REA)
 - sonar images and conditions
 - bathymetric data
 - water current information
 - mine reconnaissance
 - pictures of underwater objects
- Preparation and assistance of landing activities
 - actual situation assessment
 - guidance of the combat diver teams
 - visual escorting of landing forces on/offshore
 - communication relay
- Meanwhile the submarine could stay covert
- Observing areas which were inaccessible for conventional submarines
- In parallel while the submarine fulfils other tasks.

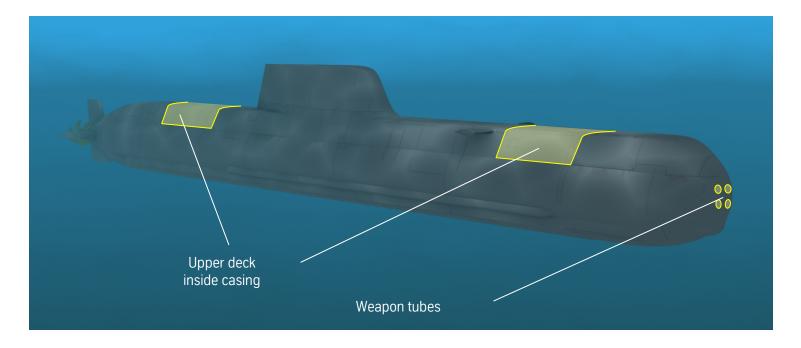






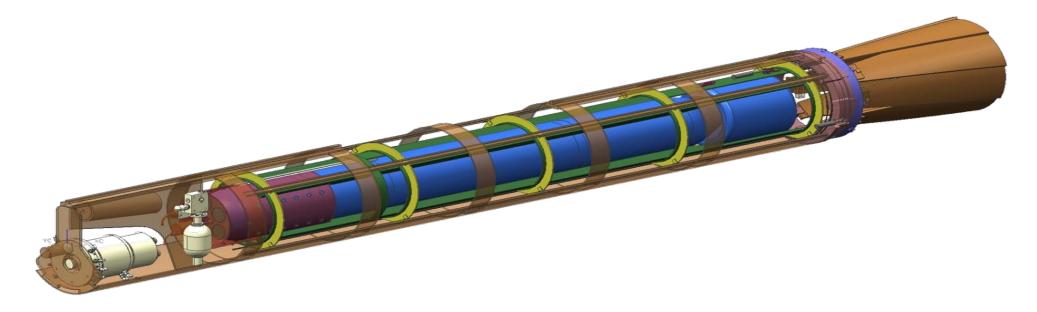
Concept Idea – UUV Launch & Recovery System for Submarines

- Capable for retrofitting on existing HDW Class Submarines
 - less conversion effort
 - easy to handle and simple interfaces
 - also for new submarine projects
- Minimized negative influence on the present submarine performance
 - no additional signatures
 - not visible if the submarine is surfaced
 - no disturbing flow noise around stowage devices
 - no further appendages
 - no increased drag or manoeuvring limitations for the submarine
 - no/minimal increased weight
 - \Rightarrow Only two options for integration UUVs on submarines.



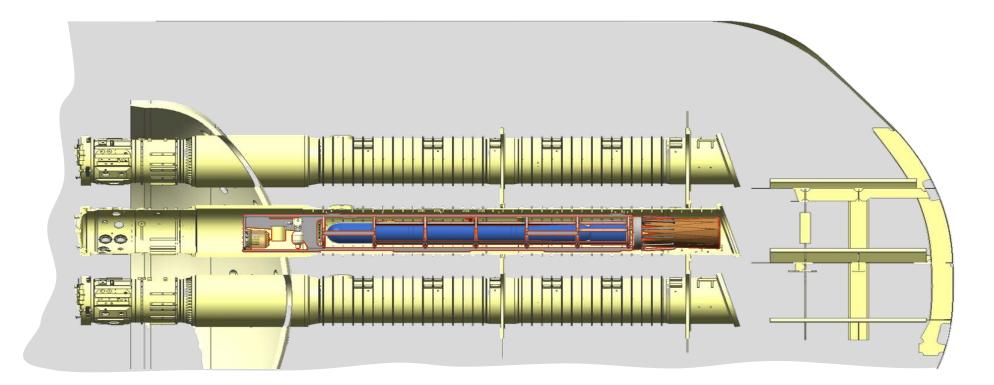


- e.g. AUV DAVID made by Diehl BGT Defences



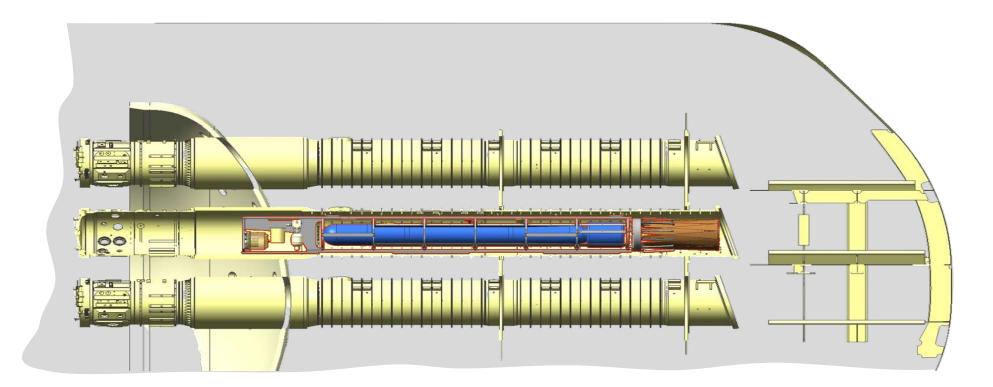


- e.g. AUV DAVID made by Diehl BGT Defences



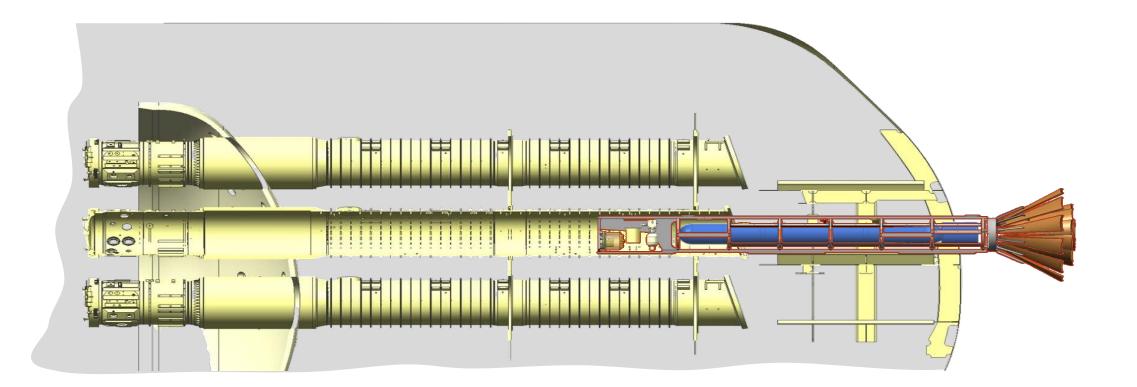


- Horizontal movement in the weapon tube

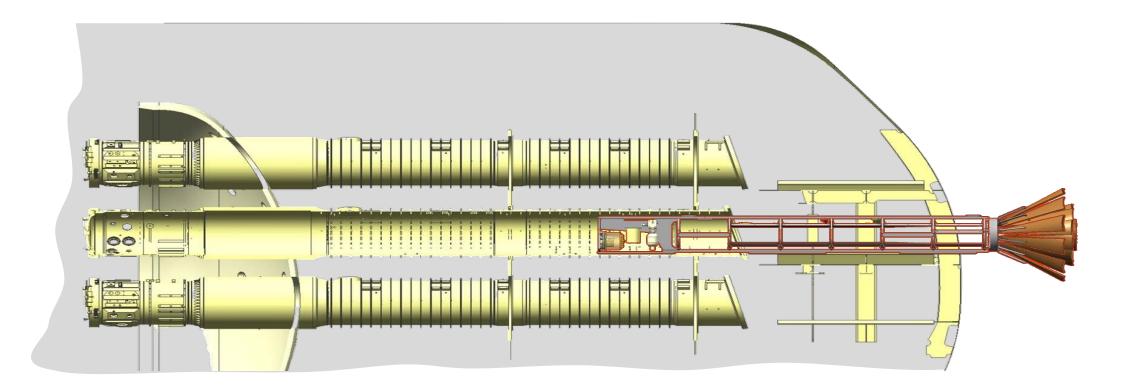




- Launching of the AUV

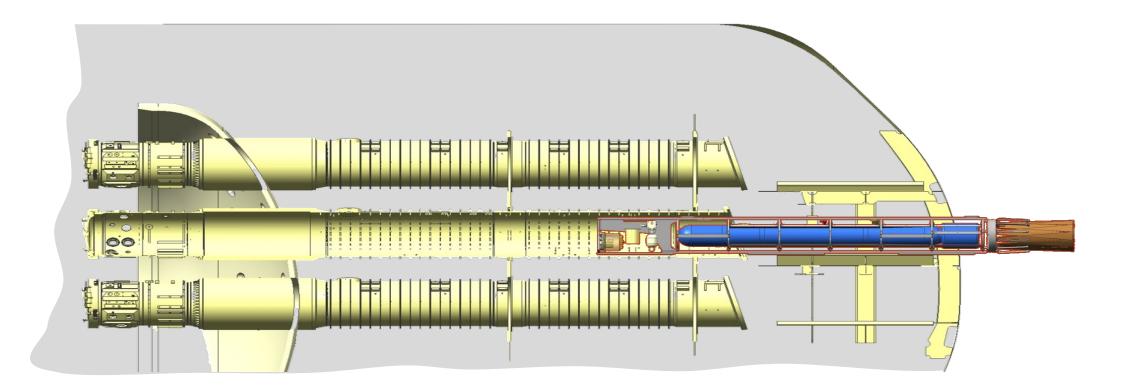


- Recovery of the AUV



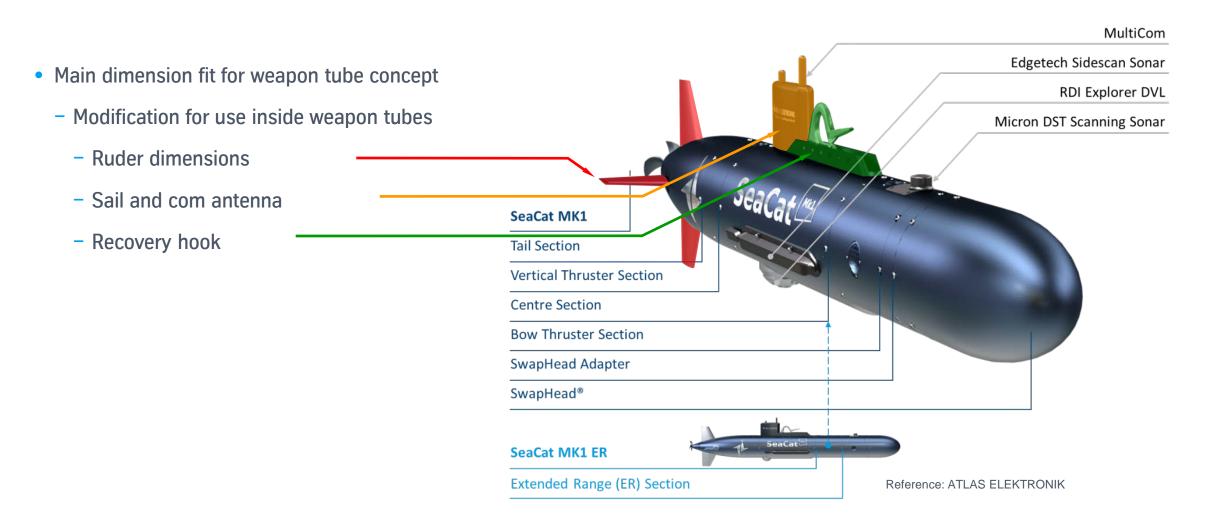


- Retraction into the weapon tube.





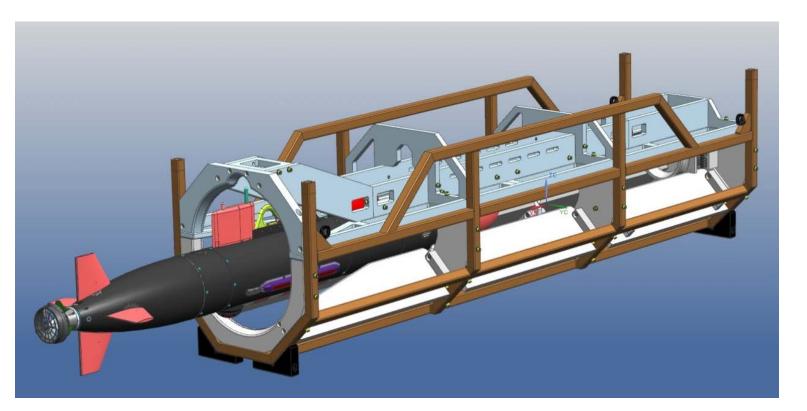
SeaCat MKI (ATLAS ELEKTRONIK)





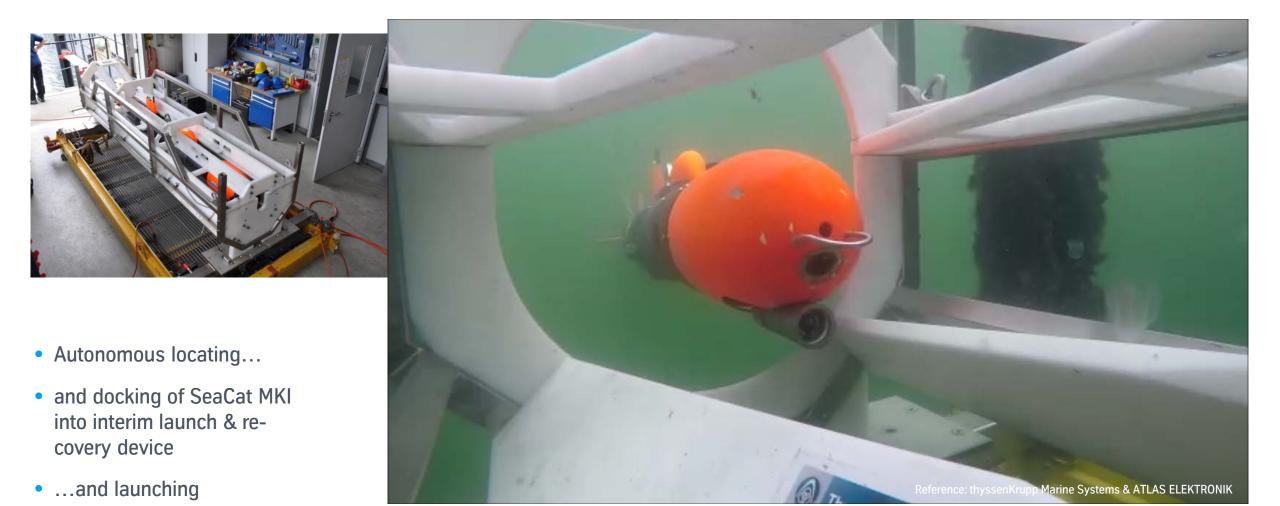
Continuation with SeaCat MKI

- Experience with launch & recovery procedure
- Next practical trials focusing
 - autonomous location
 - reacting on movements of submarine
 - data communication
- Interim launch & recovery device for SeaCat MKI





Latest Harbour Trials Summer 2015



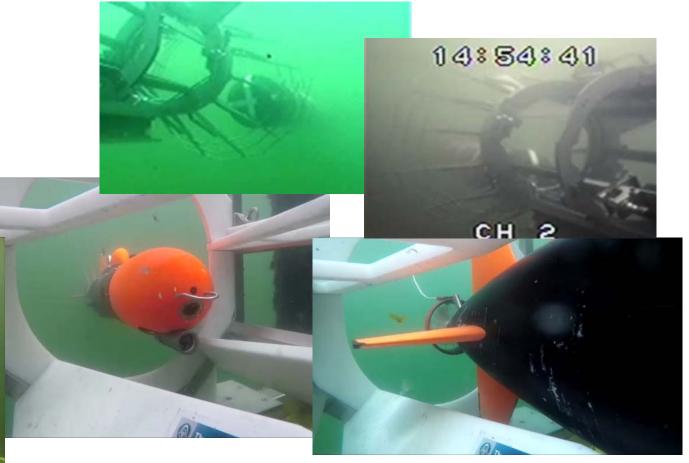
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Conclusion

- Reached Aims at launch & recovery
 - Mechanical function demonstrated
 - Drive in & out by AUV impellent
 - Autonomous locating and manoeuvring to recovery device



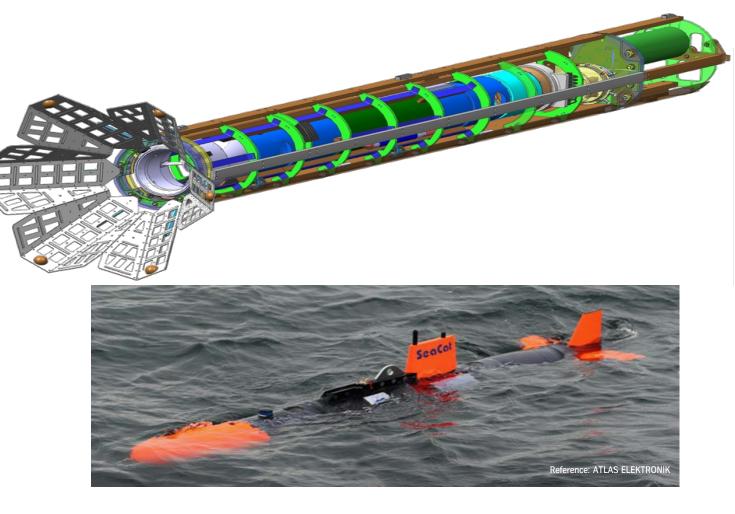




Results and Next Steps

 Functionality of the weapon tube L&R device was demonstrated at harbour trails

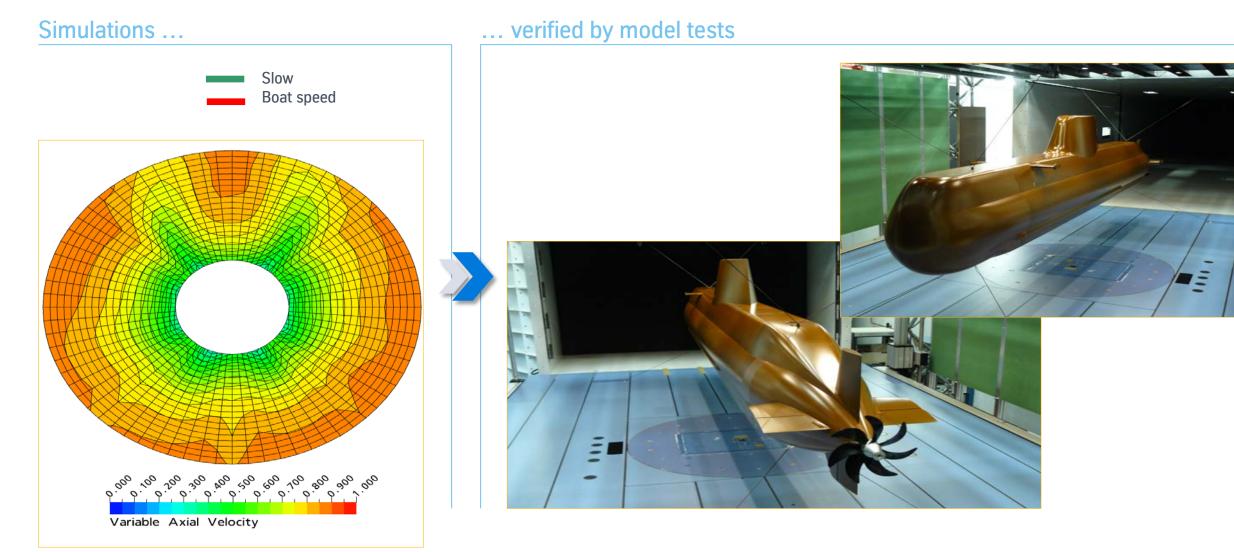
 Modification on our launch & recovery system for trials inside a weapon tube



 Changeover to the SeaCat System from ATLAS ELEKTRONIK .



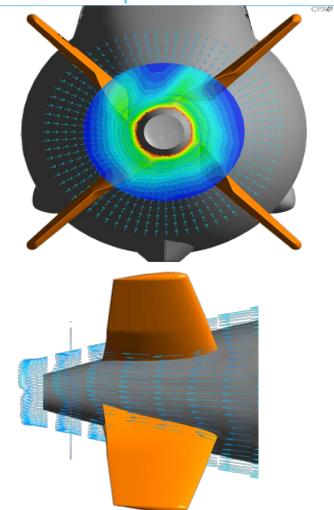
Propeller Design: Inhomogeneous Inflow to the Propeller



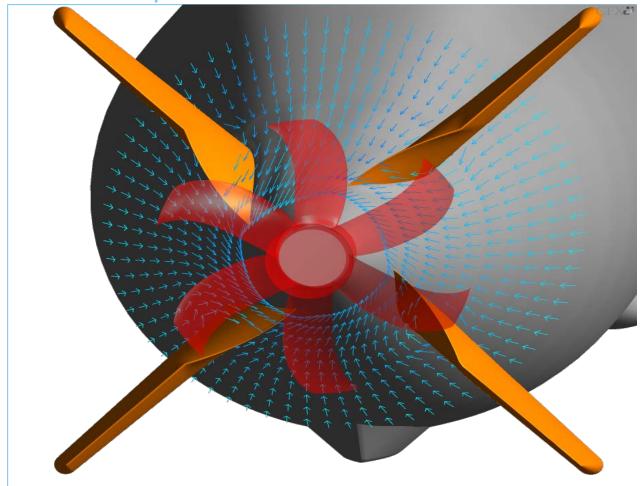


Pre-swirl Rudder

Front of the Propeller



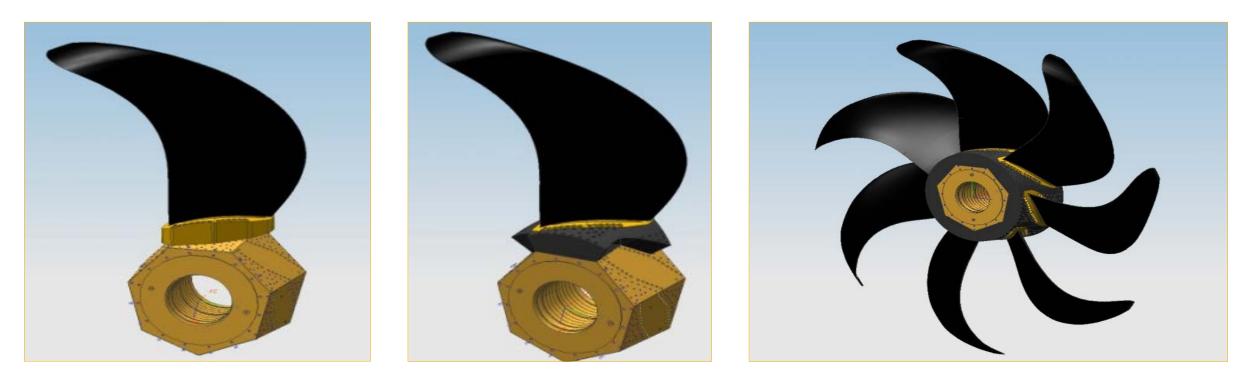
Behind the Propeller



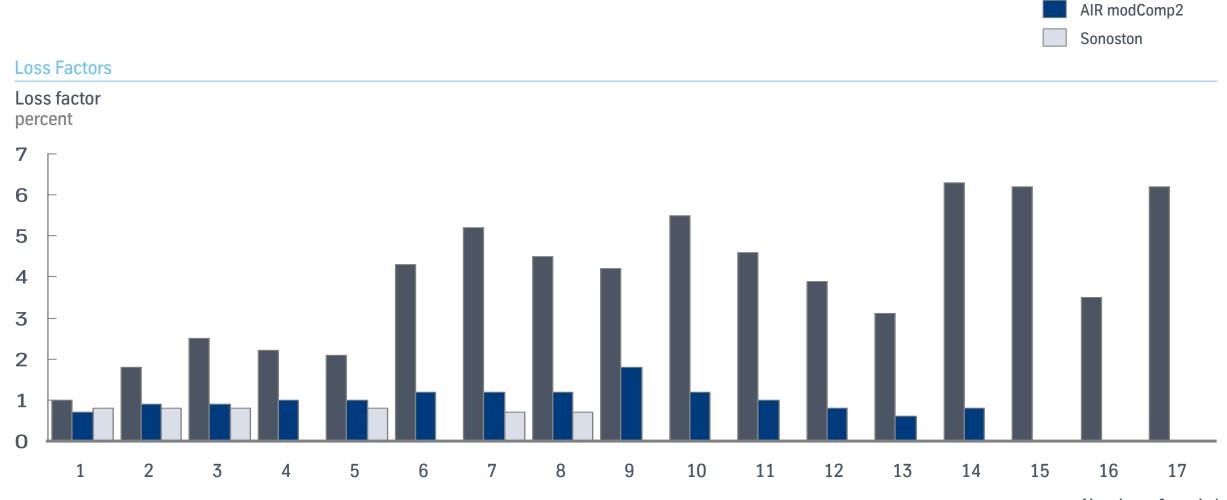


Composite Propeller - Design Principle

Blades individually screwed to the hub for ease of individual replacement







Number of mode/ Eigenfrequencies

tkMS inhouse

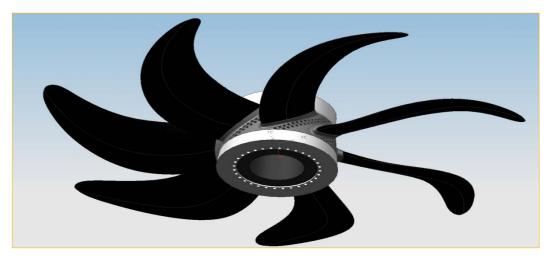
production





Comparison of modal Loss Factors of different Propellers

FRP Propeller

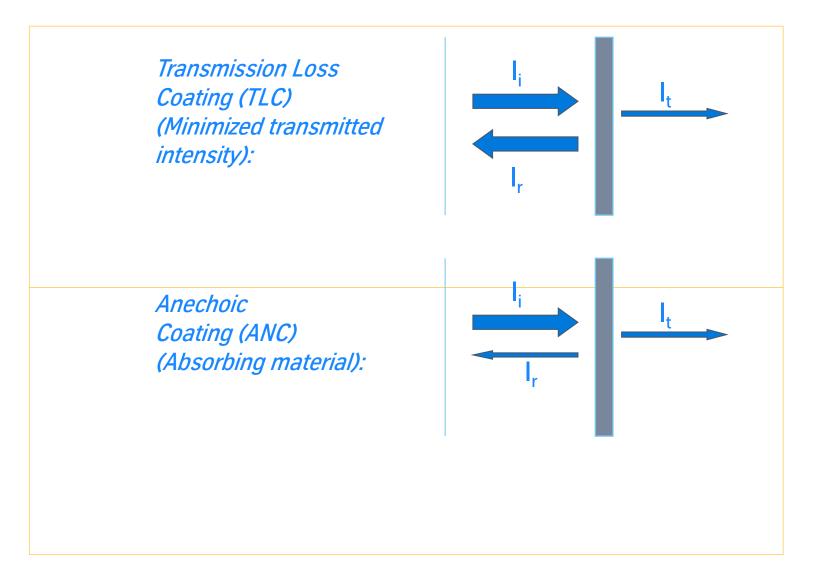


- Replaceable Blades
- Reduced Weight
- Improved Resilience
- Improved Shape and Manufacturing Precision
- Under Verification with German Navy



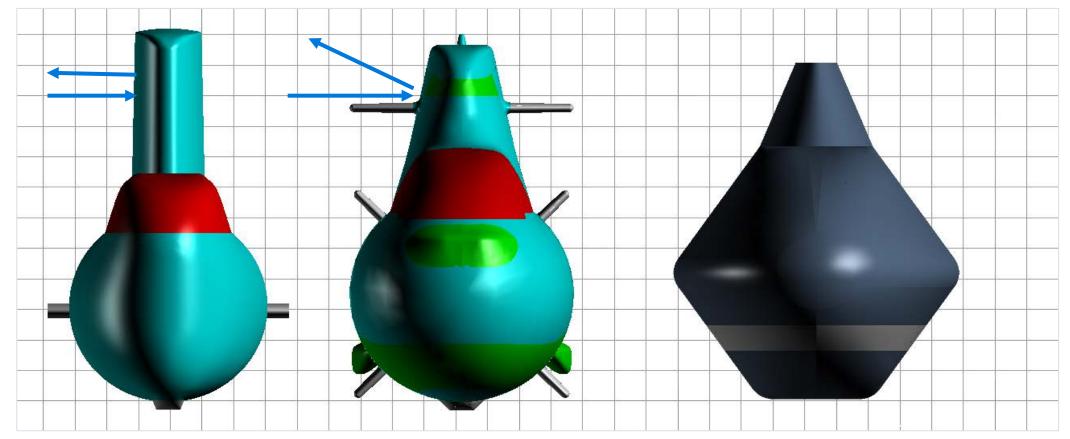


Acoustic Coating - Types





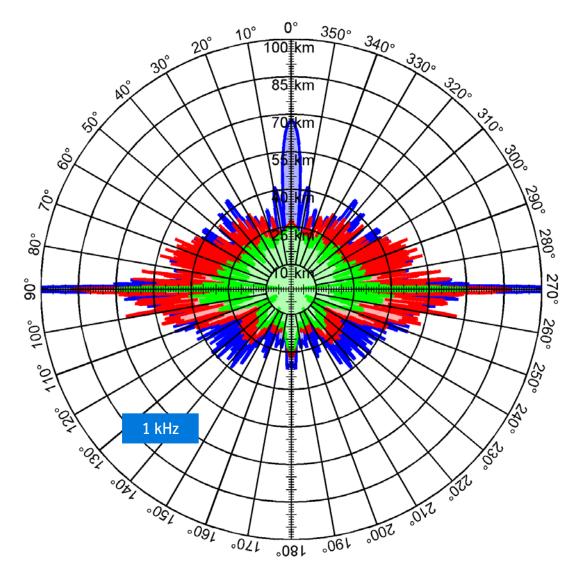
Acoustic Coating



Shaping designed to achive low target echo strength values



Acoustic Coating - Detection Range: BeTSSi *) Comparison



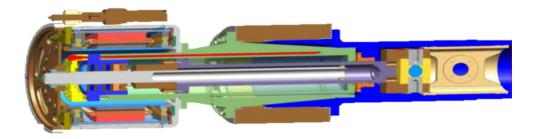
Sub	Detection Area
BeTSSi	3910 km ²
BeTSSi Coated	3111 km ²
BeTSSi Shaped	1472 km ²
Sub	Detection Range
BeTSSi	121 km

BeTSSi	121 km
BeTSSi Coated	88 km
BeTSSi Shaped	70 km

*) Standard submarine for TES simulations



Some more Examples



- Electrical rudder actuator
- UUV integration
- TCM Systems
- • • •



